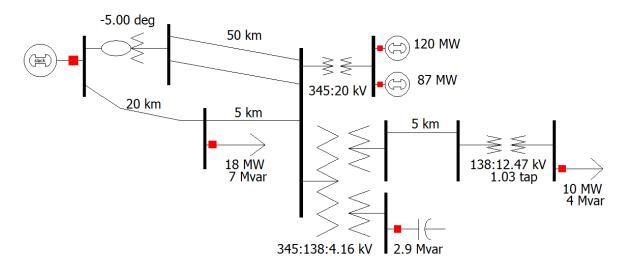
Review for ECEN 615 Exam 1

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In the system above, assume

- All transmission lines have per-unit, per-kilometer values of X=0.002, R=0.0001, B=0.01
- All the two-winding transformers have a nominal impedance of X=0.1, R=0
- The three-winding transformer has Xhl=0.15, Xhm=0.12, Xml=0.09, with R=0
- The phase-shifting transformer is subject to an impedance correction table below

Phase (degrees)	-20	0	20
Z multiplier	1	0.01	1

- The two generating units in the upper right are regulating the 345 kV bus voltage to 1.05
- Make other reasonable assumptions as necessary

Review Questions on the Example System

- 1. How do you calculate the y-bus for the example system?
- 2. What are the bus types, variables, and types of equations for the above system?
- 3. What would be the dimensions of the Jacobian?
- 4. Without solving, what do you expect for approximate P value of the slack bus?
- 5. What would the DC power flow predict? (ignoring the phase shift for this, although some DC power flow methods include it)
- 6. How would you handle var sharing between the two generators?
- 7. Under what conditions would the capacitor likely be switched out of service?
- 8. What is the likely purpose and function of the phase shifting transformer?
- 9. If the two generators reached their reactive power limit, how would that affect the way the power flow solves?

10. Assume the slack bus represents a neighboring area to which your area is contracted to export 150 MW. What is the current approximate ACE and what controls could be used to fix it?

Other Review Questions

- 11. What are the key things that happened in the 1860-1900 era for power systems?
- 12. What are the key things that happened in the 1900-1940 era for power systems?
- 13. What are the key things that happened in the 1940-1980 era for power systems?
- 14. What are the key things that happened in teh 1980-2010 era for power systems?
- 15. What are the key things that happened in the 2010-2023 era for power systems?
- 16. What are expected things in the near and far future for power systems?
- 17. What are the different time scales power systems are modeled for? What types of modeling decisions are made for those different time scales?
- 18. What makes power flow a non-linear problem and what does that mean?
- 19. How well does Newton-Raphson converge? What factors make it converge worse and better?
- 20. How do we handle generator reactive power limits in power flow?
- 21. How do we handle voltage dependent load in power flow?
- 22. What is a bus? breaker?
- 23. What are some of the different configurations for substation layout and the benefits/detriments of each?
- 24. What's the difference between node/breaker and bus/branch modeling? (EMS vs planning model)
- 25. What does topology processing do?
- 26. What are the different ways to connect a two-winding, three-phase transformer? What are they typically used for?
- 27. What is an autotransformer? Where do you see them? How are they modeled?
- 28. What are three-winding transformers used for? How are they modeled?
- 29. How are tap-changing transformers modeled?
- 30. How are phase-shifting transformers modeled?
- 31. What is an impedance correction table?
- 32. What is the difference between continuous and discrete shunt reactive power sources?
- 33. What are the differenc complexities that can occur with generator voltage/reactive power control?
- 34. What is the most computationally complex part of the power flow?
- 35. What does the power flow optimal power multiplier do?
- 36. What are the advantages/disadvantages of the dishonest NR, decoupled PF, and FDPF?
- 37. How does the DC power flow differ from the NR power flow?
- 38. What assumption does the DC power flow make with respect to real power flow?